## **Differentials for Forklifts**

Forklift Differential - A differential is a mechanical tool that could transmit rotation and torque through three shafts, frequently but not at all times using gears. It usually operates in two ways; in automobiles, it receives one input and provides two outputs. The other way a differential operates is to combine two inputs so as to produce an output that is the average, difference or sum of the inputs. In wheeled vehicles, the differential enables each of the tires to rotate at various speeds while providing equal torque to all of them.

The differential is intended to drive a pair of wheels with equivalent torque while allowing them to rotate at various speeds. While driving round corners, an automobile's wheels rotate at different speeds. Some vehicles like for instance karts operate without using a differential and use an axle in its place. Whenever these vehicles are turning corners, both driving wheels are forced to rotate at the identical speed, usually on a common axle which is driven by a simple chain-drive mechanism. The inner wheel should travel a shorter distance than the outer wheel when cornering. Without a differential, the consequence is the outer wheel dragging and or the inner wheel spinning. This puts strain on drive train, resulting in unpredictable handling, difficult driving and damage to the roads and tires.

The amount of traction necessary to move whichever vehicle would depend upon the load at that moment. Other contributing elements consist of drag, momentum and gradient of the road. Amongst the less desirable side effects of a conventional differential is that it could reduce traction under less than perfect conditions.

The torque provided to each wheel is a result of the drive axles, transmission and engine applying a twisting force against the resistance of the traction at that particular wheel. The drive train can usually supply as much torque as required unless the load is exceptionally high. The limiting element is commonly the traction under each and every wheel. Traction could be defined as the amount of torque that could be generated between the road surface and the tire, before the wheel starts to slip. The vehicle will be propelled in the planned direction if the torque utilized to the drive wheels does not go over the limit of traction. If the torque utilized to each and every wheel does go over the traction limit then the wheels would spin constantly.